



Rademacher observations, private data and boosting

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Overview

- ❖ Definition of **Rademacher observations**, rados
- ❖ Surrogate minimization with examples = surrogate minimization with rados
- ❖ An efficient **boosting algorithm** to learn from rados + Experiments
- ❖ Rados allow to **protect information** in examples from many standpoints: computational, algebraic, geometric and differential privacy

Learning setting

- ❖ Learning sample $\mathcal{S} \doteq \{(\mathbf{x}_i, y_i), i = 1, 2, \dots, m\}$ $\mathbf{x}_i \in \mathbb{R}^d$ $y_i \in \{-1, 1\}$
- ❖ Sampled according to unknown but fixed distribution \mathcal{D}
- ❖ Objective: find algorithm \mathcal{A} returning classifier $h \in \mathcal{H}$ with small true risk $\mathbb{E}_{\mathcal{D}}[1_{yh(\mathbf{x}) \leq 0}]$
- ❖ In practice, focus on a surrogate $\varphi(x) \geq 1_{x \leq 0}$ and minimize

$$\mathbb{E}_{\mathcal{S}}[\varphi(yh(\mathbf{x}))]$$

- ❖ Example:

$$\varphi(x) = \log(1 + \exp(-x)) \leftarrow \text{logistic loss}$$

$$\begin{aligned} \mathcal{H} &= \text{linear classifiers} \\ h(\mathbf{x}) &\doteq \boldsymbol{\theta}^\top \mathbf{x} \end{aligned}$$

From examples to rados

Rademacher observations

- ❖ Learning sample $\mathcal{S} \doteq \{(\mathbf{x}_i, y_i), i = 1, 2, \dots, m\}$ $\mathbf{x}_i \in \mathbb{R}^d$ $y_i \in \{-1, 1\}$



input

Rademacher
observations
design algorithm



Rademacher observations

❖ Learning sample $\mathcal{S} \doteq \{(\mathbf{x}_i, y_i), i = 1, 2, \dots, m\}$ $\mathbf{x}_i \in \mathbb{R}^d$ $y_i \in \{-1, 1\}$

❖ Compute products $y_i \cdot \mathbf{x}_i$

$$\begin{array}{c} y_1 \cdot \mathbf{x}_1 \\ y_2 \cdot \mathbf{x}_2 \\ \vdots \\ y_m \cdot \mathbf{x}_m \end{array}$$

Do all products



Rademacher observations

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❖ Compute products $y_i \cdot \mathbf{x}_i$

$$y_1 \cdot \mathbf{x}_1$$

$$y_2 \cdot \mathbf{x}_2$$

$$\vdots$$

$$y_m \cdot \mathbf{x}_m$$

Repeat...

Do all products



Rademacher observations

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$$\begin{array}{c} y_1 \cdot \mathbf{x}_1 \\ y_2 \cdot \mathbf{x}_2 \\ \vdots \\ y_m \cdot \mathbf{x}_m \end{array}$$

// can be (non) random,
// (non) i.i.d.,
// learned from data,
etc.

pick

$$\boldsymbol{\sigma} \in \Sigma_m$$

$$\Sigma_m \doteq \{-1, 1\}^m$$

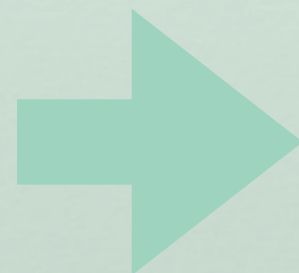


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combine

$$1/2 \cdot \sum_i (\sigma_i + y_i) \cdot \mathbf{x}_i$$



$$\boldsymbol{\sigma} \in \Sigma_m$$

\doteq

$\pi_{\boldsymbol{\sigma}}$

1 rado

output

$$\Sigma_m \doteq \{-1, 1\}^m$$

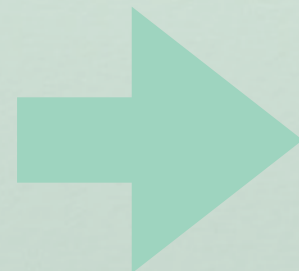


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$$1/2 \cdot \sum_i (\sigma_i + y_i) \cdot \mathbf{x}_i \quad \doteq$$

combine

for each i , either y_i or 0

$$\equiv \sum_{i: \sigma_i = y_i} y_i \mathbf{x}_i$$

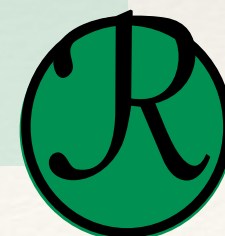
$$\sigma \in \Sigma_m$$

$$\Sigma_m \doteq \{-1, 1\}^m$$

π_σ

1 rado

output

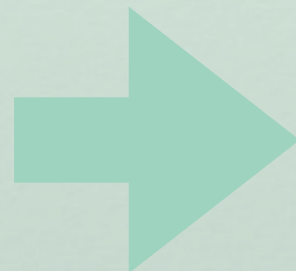


Rademacher observations

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another combination

$$1/2 \cdot \sum_i (\sigma'_i + y_i) \cdot \mathbf{x}_i \quad \doteq$$



pick

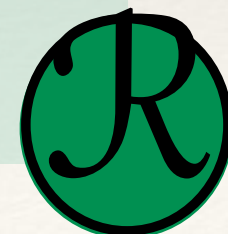
$$\sigma' \in \Sigma_m$$

$$\Sigma_m \doteq \{-1, 1\}^m$$

π_σ

$\pi_{\sigma'}$

2 rados



Rademacher observations

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❖ Compute products $y_i \cdot \mathbf{x}_i$

$y_1 \cdot \mathbf{x}_1$
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 \vdots
 $y_m \cdot \mathbf{x}_m$

... and so on

Σ

π_{σ_1}

π_{σ_2}

\vdots

π_{σ_n}

n radios

$n \sigma$

still defined in \mathcal{X}



Why rados ?

Rado-loss factorization Thm



- ❖ Learning sample $\mathcal{S} \doteq \{(\mathbf{x}_i, y_i), i = 1, 2, \dots, m\}$ $\mathbf{x}_i \in \mathbb{R}^d$ $y_i \in \{-1, 1\}$

Loss described on
examples

$$F_{\log}(\mathcal{S}, \boldsymbol{\theta}) \doteq \frac{1}{m} \sum_{i=1}^m \log(1 + \exp(-y_i \boldsymbol{\theta}^\top \mathbf{x}_i))$$

Loss described on
rados

$$F_{\exp}^r(\mathcal{S}, \boldsymbol{\theta}, \mathcal{U}) \doteq \frac{1}{n} \sum_{\boldsymbol{\sigma} \in \mathcal{U}} \exp(-\boldsymbol{\theta}^\top \boldsymbol{\pi}_{\boldsymbol{\sigma}})$$

$$\mathcal{U} \subseteq \Sigma_m$$

Rado-loss factorization Thm



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$$\mathcal{U} \subseteq \Sigma_m$$

Thm

$$F_{\log}(\mathcal{S}, \boldsymbol{\theta}) = \log(2) + \frac{1}{m} \log F_{\text{exp}}^r(\mathcal{S}, \boldsymbol{\theta}, \Sigma_m)$$

- ❖ Hence,

$$\arg \min_{\boldsymbol{\theta}} F_{\log}(\mathcal{S}, \boldsymbol{\theta}) = \arg \min_{\boldsymbol{\theta}} F_{\text{exp}}^r(\mathcal{S}, \boldsymbol{\theta}, \Sigma_m)$$

Same classifier...

Bottleneck

- ❖ Learning sample $\mathcal{S} \doteq \{(\mathbf{x}_i, y_i), i = 1, 2, \dots, m\}$ $\mathbf{x}_i \in \mathbb{R}^d$ $y_i \in \{-1, 1\}$

Loss described on
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Loss described on
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$$F_{\exp}^r(\mathcal{S}, \boldsymbol{\theta}, \mathcal{U}) \doteq \frac{1}{n} \sum_{\boldsymbol{\sigma} \in \mathcal{U}} \exp(-\boldsymbol{\theta}^\top \boldsymbol{\pi}_{\boldsymbol{\sigma}})$$

$$\mathcal{U} \subseteq \Sigma_m$$

Thm

$$F_{\log}(\mathcal{S}, \boldsymbol{\theta}) = \log(2) + \frac{1}{m} \log F_{\exp}^r(\mathcal{S}, \boldsymbol{\theta}, \Sigma_m)$$

$$\mathcal{U} = \Sigma_m$$

- ❖ Hence,

$$\arg \min_{\boldsymbol{\theta}} F_{\log}(\mathcal{S}, \boldsymbol{\theta}) = \arg \min_{\boldsymbol{\theta}} F_{\exp}^r(\mathcal{S}, \boldsymbol{\theta}, \Sigma_m)$$

Same classifier... but $|\mathcal{U}| = 2^m$...

Workaround



❖ Let $\mathcal{U} \sim_{i.u.d.} \Sigma_m$ with $|\mathcal{U}| = n$. Then with probability $\geq 1 - \eta$ over the sampling of \mathcal{U} ,

$$F_{\log}(\mathcal{S}, \theta) \leq \log(2) + \frac{1}{m} \log F_{\exp}^r(\mathcal{S}, \theta, \mathcal{U}) + O\left(\frac{\rho}{m^\beta} \cdot \sqrt{\frac{r_\theta \pi_r^*}{n} + \frac{d}{nm} \log \frac{2en}{d\eta}}\right)$$

$(\forall \beta < 1/2)$

- ❖ Holds for **any** learning sample \mathcal{S} ,
- ❖ Provided a sufficient number of rados, the minimization of $F_{\exp}^r(\mathcal{S}, \theta, \mathcal{U})$ is a **good proxy** for the minimization of $F_{\log}(\mathcal{S}, \theta)$

Improved workaround

$$\forall \Sigma_r \subseteq \Sigma_m$$

❖ Let $\mathcal{U} \sim_{i.u.d.} \Sigma_r$ with $|\mathcal{U}| = n$. Then with probability $\geq 1 - \eta$ over the sampling of \mathcal{U} ,

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$$(\forall \beta < 1/2)$$

+Q

Improved workaround

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$(\forall \beta < 1/2)$

Authorizes sophisticated design mechanisms for Σ_r to solve particular problems.



Any efficient learning algorithm
with rados ?

$\min_{\theta} F_{\text{exp}}^r(\mathcal{S}, \theta, \mathcal{U})$



Radoboost

Algorithm 1 Rado boosting (RADOBOOST)

Input set of rados $S^r \doteq \{\pi_1, \pi_2, \dots, \pi_n\}; T \in \mathbb{N}_*$;

Step 1 : let $\theta_0 \leftarrow \mathbf{0}, w_0 \leftarrow (1/n)\mathbf{1}$;

Step 2 : **for** $t = 1, 2, \dots, T$

 Step 2.1 : $[d] \ni \iota(t) \leftarrow \text{WFI}(S^r, w_t)$;

 Step 2.2 : let

$$r_t \leftarrow \frac{1}{\pi_{*\iota(t)}} \sum_{j=1}^n w_{tj} \pi_{j\iota(t)} ; \quad (1)$$

$$\alpha_t \leftarrow \frac{1}{2\pi_{*\iota(t)}} \log \frac{1+r_t}{1-r_t} ; \quad (2)$$

 Step 2.3 : **for** $j = 1, 2, \dots, n$

$$w_{(t+1)j} \leftarrow w_{tj} \cdot \left(\frac{1 - \frac{r_t \pi_{j\iota(t)}}{\pi_{*\iota(t)}}}{1 - r_t^2} \right) ; \quad (3)$$

Return θ_T defined by $\theta_{Tk} \doteq \sum_{t:\iota(t)=k} \alpha_t$, $\forall k \in [d]$;

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 Step 2.1 : $[d] \ni l(t) \leftarrow \text{WFI}(\mathcal{S}^r, w_t)$;

 Step 2.2 : let

Input: set of rados

Weak choice of a feature

$$r_t \leftarrow \frac{1}{\pi_{*l(t)}} \sum_{j=1}^n w_{tj} \pi_{jl(t)} ; \quad (1)$$

$$\alpha_t \leftarrow \frac{1}{2\pi_{*l(t)}} \log \frac{1+r_t}{1-r_t} ; \quad (2)$$

Step 2.3 : **for** $j = 1, 2, \dots, n$

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Input: set of rados

Weak choice of a feature

normalized rado edge

Radoboost

Algorithm 1 Rado boosting (RADOBOOST)

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leveraging coefficient

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Final classifier can be used **directly** on new observations

Radoboost... boosts !

- ❖ Weak learning assumption (WLA): $\exists \gamma > 0$ such that $|r_t| \geq \gamma, \forall t$
- ❖ Then after T rounds of boosting, the output θ_T of RadoBoost meets:

Thm

$$F_{\text{exp}}^r(\mathcal{S}, \theta_T, \mathcal{U}) \leq \exp(-T\gamma^2/2)$$

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- ❖ So, since $F_{\log}(\mathcal{S}, \theta_T) = \log(2) + \frac{1}{m} \log F_{\text{exp}}^r(\mathcal{S}, \theta_T, \Sigma_m)$,
- ❖ we have

$$F_{\log}(\mathcal{S}, \theta_T) \leq \log(2) - \frac{T\gamma^2}{2m} \quad \text{If } \mathcal{U} = \Sigma_m \dots$$

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- ❖ ... in the general case ($\forall \mathcal{U}$),

Thm

$$F_{\log}(\mathcal{S}, \theta_T) \leq \log(2) - \frac{T\gamma^2}{2m} + Q' \quad \text{not a function of } T$$

Experiments

Experiments (some)

($T = 1000$)

❖ RadoBoost vs AdaBoost

number of rados / examples
 $n = \min\{1000, \text{train fold size}/2\}$

Domain	m	d	AdaBoost $\text{err} \pm \sigma$	AdaBoost(n) $\text{err} \pm \sigma$	$\frac{n}{m}$	RadoBoost $\text{err} \pm \sigma$	$\frac{n}{2^m}$
Abalone	4 177	8	22.96 \pm 1.44	23.20 \pm 1.44	0.24	25.14 \pm 1.83	[3:–[1:3]]
Wine-white	4 898	11	30.93 \pm 3.42	30.44 \pm 3.25	0.20	32.48 \pm 3.55	[3:–[1:3]]
Magic	19 020	10	21.07 \pm 0.98	20.91 \pm 0.99	0.05	22.75 \pm 1.51	[3:–[5:3]]
EEG	14 980	14	46.04 \pm 1.38	44.36 \pm 1.99	0.07	44.23 \pm 1.73	[4:–[4:3]]
Hardware	28 179	95	16.82 \pm 0.72	16.76 \pm 0.73	0.04	7.61 \pm 3.24	[2:–[8:3]]
Twitter	583 250	77	53.75 \pm 1.48	53.09 \pm 11.23	[1:–3]	6.00 \pm 0.77	[1:–[1:5]]
SuSy	5 000 000	17	27.76 \pm 0.14	27.43 \pm 0.19	[2:–4]	27.26 \pm 0.55	[1:–[1:6]]
Higgs	11 000 000	28	42.55 \pm 0.19	45.39 \pm 0.28	[9:–5]	47.86 \pm 0.06	[1:–[1:7]]

$9 \cdot 10^{-5}$

vs

$10^{-100000000}$

Improved workaround

$$\forall \Sigma_r \subseteq \Sigma_m$$



❖ Let $\mathcal{U} \sim_{i.u.d.} \Sigma_r$ with $|\mathcal{U}| = n$. Then with probability $\geq 1 - \eta$ over the sampling of \mathcal{U} ,

$$F_{\log}(\mathcal{S}, \theta) \leq \log(2) + \frac{1}{m} \log F_{\exp}^r(\mathcal{S}, \theta, \mathcal{U}) + O\left(\frac{\rho}{m^\beta} \cdot \sqrt{\frac{r_\theta \pi_r^*}{n} + \frac{d}{nm} \log \frac{2en}{d\eta}}\right) + Q$$

$(\forall \beta < 1/2)$

$$\theta \in \mathcal{B}(0, r_\theta)$$

Authorizes sophisticated design mechanisms for Σ_r to solve particular problems.

Example: privacy

Rados and privacy

- ❖ Protection guarantees:
 - ❖ Crafting of **differentially private (DP)** rados from examples
 - ❖ **Computational hardness** of approximate sparse recovery of examples from rados
 - ❖ **Computational hardness** of pinpointing examples used to craft rados
 - ❖ **Geometric and algebraic hardness** of recovering examples from rados
 - ❖ Learning with rados from **differentially private** (noisified) examples.

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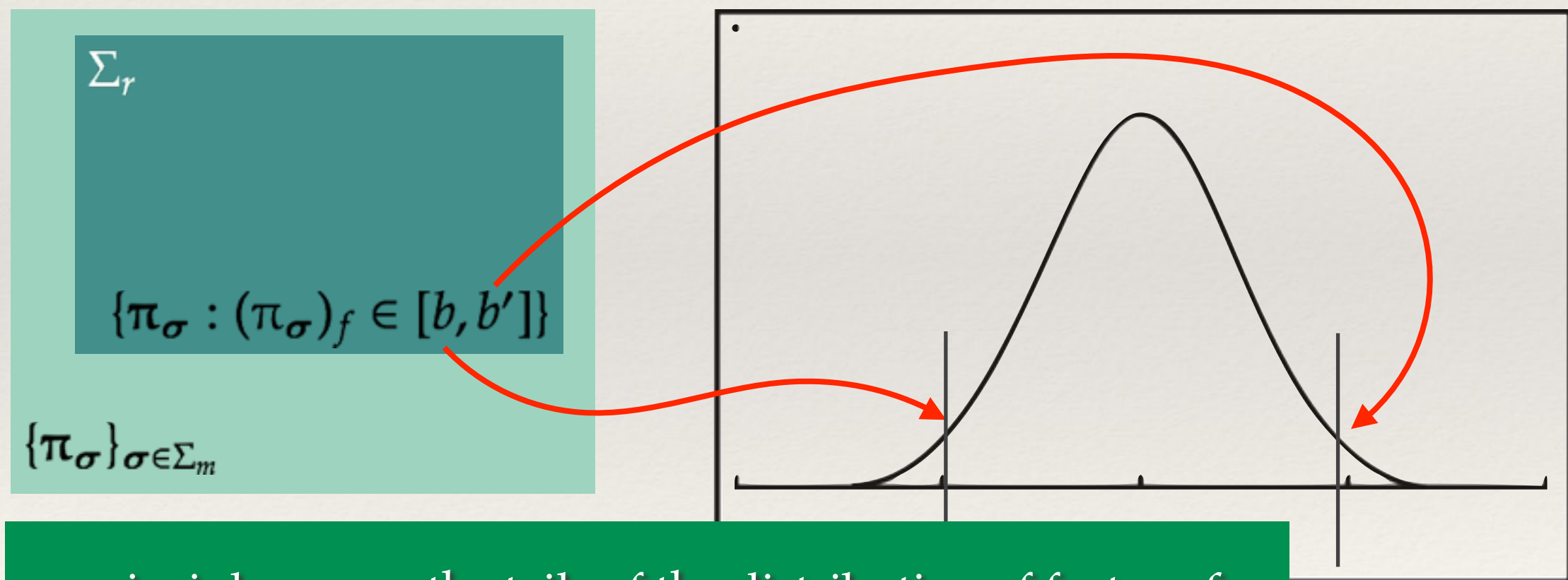
- ❖ **Definition:** statistical protection of one sensitive feature f so that changing one *example* (in \mathcal{S}) does not change **significantly** the (statistical) distribution of that feature in *rados* (wrt Σ_r):

$$\mu(f \text{ in rados}|\mathcal{S}) \leq \mu(f \text{ in rados}|\mathcal{S}') \cdot \exp(\epsilon) + \delta$$

\mathcal{R} DP-rados from non-DP examples

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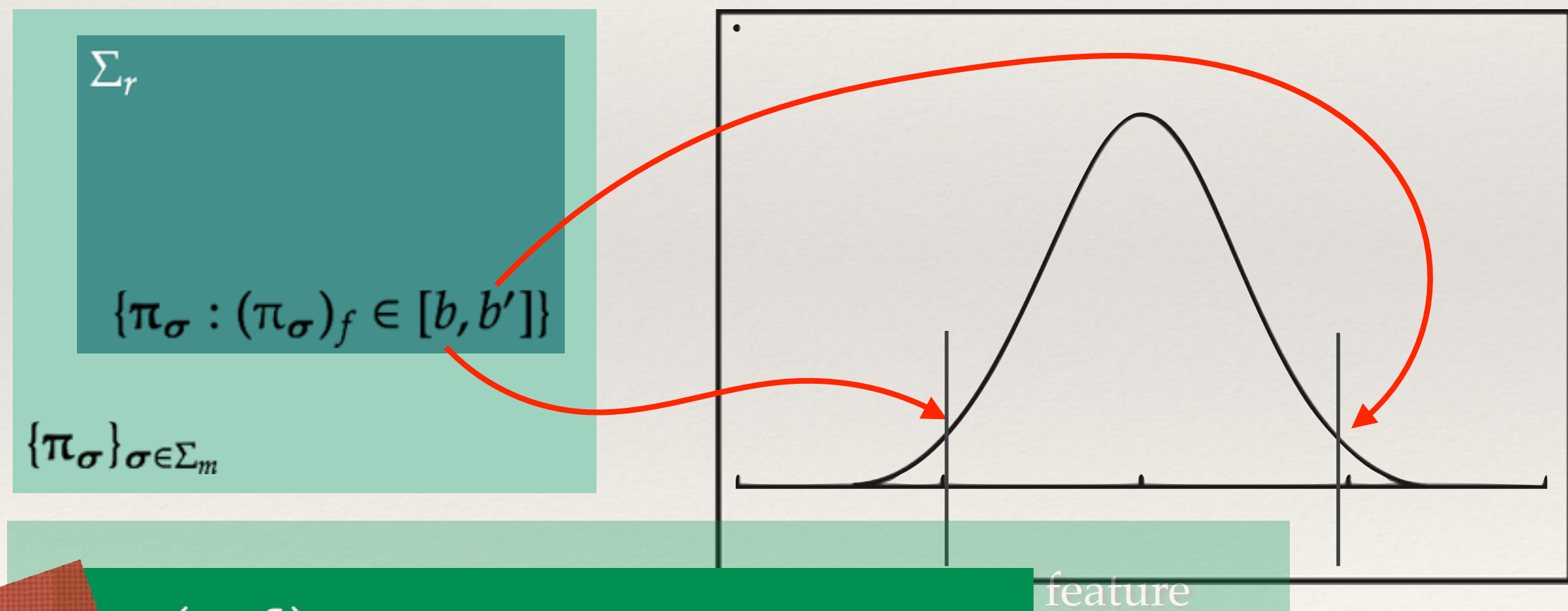
principle: prune the tails of the distribution of feature f

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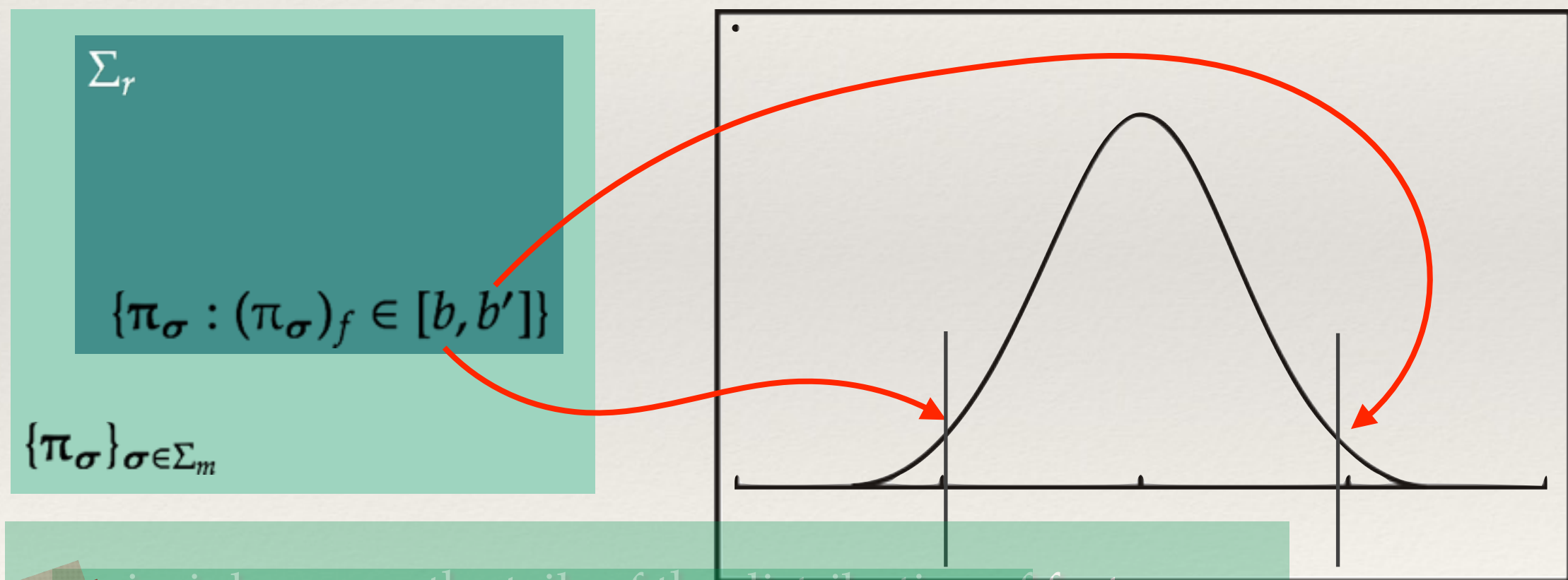


Thm $\Rightarrow (\epsilon, \delta)$ -differential privacy on feature f

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Thm

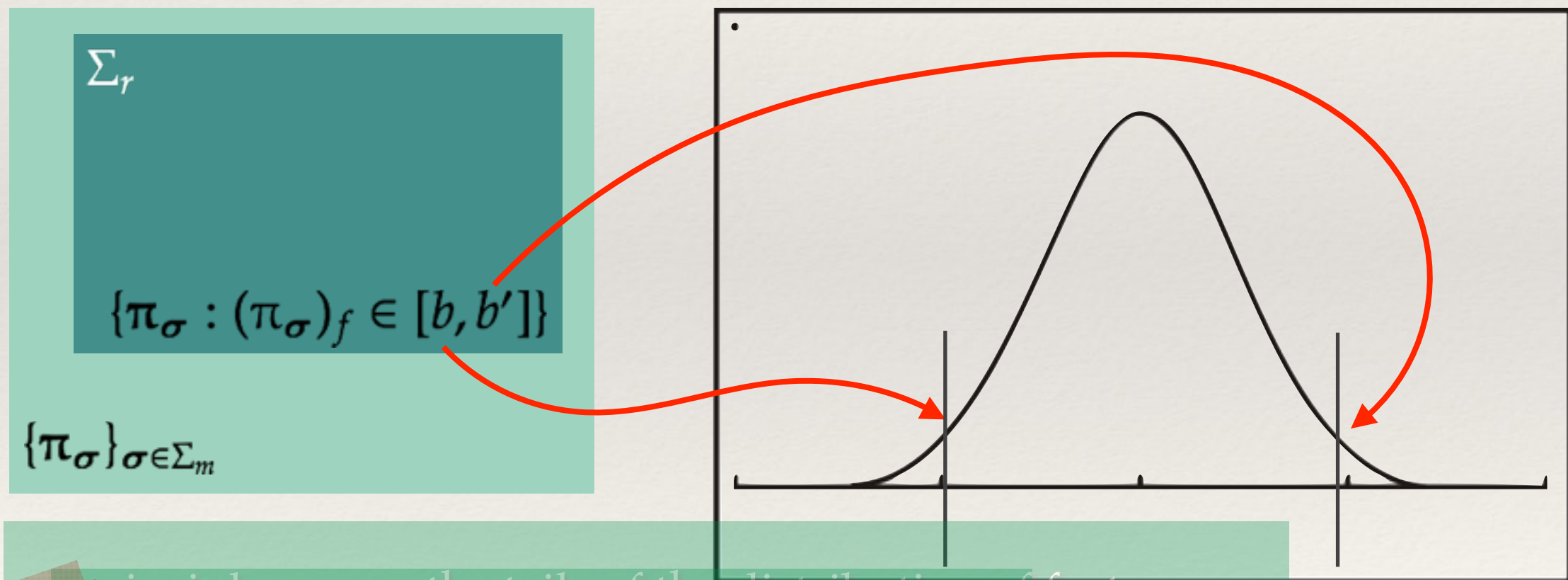
There exists an efficient rejection sampling to implement the mechanism

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principle: prune the tails of the distribution of feature

This mechanism does not require noise injection!

- ❖ Problem (informal): a malicious agency \mathcal{A} has a big database of people identities \mathcal{S} . \mathcal{A} intercepts some set of rados \mathcal{S}^r sent over the network.
- ❖ Question: does there exist a subset of \mathcal{S} of size m that may have been used to *approximately* craft the rados in \mathcal{S}^r ?

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NP-HARD

- ❖ Suppose \mathcal{A} is given *only* a set of rados. \mathcal{A} knows **nothing else** about the examples \mathcal{S} , except that all lie in a ball of radius R .
- ❖ Then there exists a set of examples \mathcal{S}' with just *one* more example, that produces the *same* rados but lies very far away (in Hausdorff distance)

$$D_H(\mathcal{S}, \mathcal{S}') = \Omega\left(\frac{R \log d}{\sqrt{d} \log m}\right) \quad (m \geq 2^d)$$

$$D_H(\mathcal{S}, \mathcal{S}') = \Omega\left(\frac{R}{\sqrt{d}}\right) \quad (\text{Otherwise})$$

- ❖ Suppose \mathcal{A} is given *only* a set of radii. \mathcal{A} knows **nothing else** about the examples \mathcal{S} , except that all lie in a ball of radius R .

- ❖ Then there exists a set of radii with just one radius but large covering distance)

Hardness does not rely on the computational power at hand

$$D_H(\mathcal{S}, \mathcal{S}) = \Omega\left(\frac{R}{\sqrt{d}}\right)$$

(Otherwise)

Summary

- ❖ Learning over (small) sets of rados
 - ❖ may be as **efficient** as learning over examples
 - ❖ can **ensure additional properties** that are hard to meet with examples alone.
- ❖ The final classifier can be used **as is** to classify new observations.
- ❖ So far, we made no optimisation of the rados set for learning, just **plain random selection** — this was sufficient to beat supervised learning algorithms on fairly big domains :-)
- ❖ **Other domains** may benefit from the rado representation (incl. on-line and distributed learning).

Thank you ! Questions ?

DP-rados from non-DP examples

- ❖ RadoBoost + rados *vs.* RadoBoost + DP rados
- ❖ f = random binary feature

